IN THE CLAIMS

Please amend the claims as follows:

Claims 1-7 (Canceled).

Claim 8 (New): An elastic elastomer joint configured to act as a spring member of a vehicle suspension device, the joint defining an axis of rotation and comprising:

an inner reinforcement and an outer reinforcement connected by an elastic elastomer material,

wherein the joint is configured to be fixed by the outer reinforcement to a longitudinal oscillating arm connected to an axis of a vehicle wheel and by the inner reinforcement to the vehicle chassis, and is configured to oppose a torsional restoring force when subjected to a torsional stress about the axis of rotation, wherein the outer reinforcement comprises an angular adjusting mechanism of the joint about the axis of rotation relative to the longitudinal oscillating arm.

Claim 9 (New): An elastic elastomer joint according to claim 8, wherein the angular adjustment mechanism extends radially from a periphery of the outer reinforcement.

Claim 10 (New): An elastic elastomer joint according to claim 8, wherein the angular adjustment mechanism comprises at least one elongate hole in a form of an arc of a circle centered on the axis of rotation configured to be placed level with a hole of the longitudinal oscillating arm to fix the joint to the longitudinal oscillating arm.

Claim 11 (New): An elastic elastomer joint according to claim 8, wherein the angular adjustment mechanism comprises at least one elongate hole with notches in a form of an arc of a circle centered on the axis of rotation.

Claim 12 (New): An elastic elastomer joint according to claim 8, wherein the angular adjustment mechanism comprises at least two lugs extending radially over a periphery of the outer reinforcement and each comprising an elongate hole.

Claim 13 (New): An elastic elastomer joint according to claim 8, wherein the angular adjustment mechanism comprises at least first and second holes, the first hole corresponding to a hole in the longitudinal oscillating arm for a specified angular position of the longitudinal oscillating arm relative to the axis of rotation, the second hole corresponding to another hole of the longitudinal oscillating arm for another specified angular position of the longitudinal oscillating arm relative to the axis of rotation.

Claim 14 (New): An elastic elastomer joint according to claim 13, wherein the angular adjustment mechanism comprises at least two lugs extending radially from a periphery of the outer reinforcement, and each comprising at least two holes.